



Surveying Engineering Lecture 3: Bearings

Dr. Eng. Hassan Mohamed Hassan <u>Hassan.hussein@feng.bu.edu.eg</u> Geomatics Department





- 1. Coordinate Systems
- 2. Plane Coordinate System
- 3. WCB-QB, FB-BB
- 4. Coordinates main concept

Coordinate Systems

- 1- Geographic or geodetic coordinate systems ($\Phi,\Omega,h)$ or (X, Y ,Z)
- 2- Plane coordinates: Cartesian (X,Y) or (E,N)





Plane Coordinate System

1- Cartesian (X,Y) or (E,N)



Whole Circle Bearing (WCB)

1- Azimuth of the line (WCB): It's the angle measured from the North direction to the line in the clockwise direction.



If α negative then add 360° if $\alpha > 360°$ then subtract 360°.

Forward Bearing (FB) and Back Bearing (BB)

1- The relation between the Forward Bearing (FB) and Back Bearing (BB).



Quadrant Bearing (QB)

It is the angle between the line and North-South direction whichever closer in clockwise or anticlockwise direction.



Coordinates main concept

1- Calculation of an angle between 2 bearings:

 $\propto_{_{AC}}-\propto_{_{AB}}=B\,A\,C$. Angle always in clockwise direction

2- Calculation of components of a line from length and bearing $\Delta E_{AB} = L_{AB} \sin \propto A_{AB}$

$$\Delta N_{AB} = L_{AB} \cos \propto_{AB}$$

If coordinates of A are given, then:

$$E_{B} = E_{A} + L_{AB} \sin \infty_{AB}$$
$$N_{B} = N_{A} + L_{AB} \cos \infty_{AB}$$



Calculation of length and bearing from coord.

1- Calculation of length of a line from coordinates:



2- Calculation of bearing of a line from coordinates:

$$\mathbf{Q}_{\mathrm{AB}} = \tan^{-1} \frac{\left| \Delta E_{\mathcal{AB}} \right|}{\left| \Delta N_{\mathcal{AB}} \right|}$$

First without signs, then take sign into consideration.

$\Delta E = -ve$	$\Delta E = +ve$
$\Delta N = +ve$	$\Delta N = +ve$
$\mathcal{X}_{AB}=360-\mathcal{Q}_{AB}$	$\mathcal{X}_{AB} = \mathcal{Q}_{AB}$
$\Delta E = -ve$	$\Delta E = +ve$
$\Delta N = -ve$	$\Delta \! N = - v e$
$\propto_{AB} = 180 + Q_{AB}$	$\propto_{AB} = 180 - Q_{AB}$

Supplementary files:

- https://www.youtube.com/watch?v=L_HqYnLx3sl
- https://www.youtube.com/watch?v=vB8bhi5vbg4
- https://www.youtube.com/watch?v=IM6kWrgsGYw

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Thanks

Dr.Eng. Hassan Mohamed